

LAMPIRAN A
SCRIPT PERANGKAT KERAS SUB-SISTEM *MONITORING*

```
#include "ACS712.h"

#include <Wire.h>

#include <BH1750.h>

#include "ThingSpeak.h"

#include "WiFiEsp.h"

#include "EmonLib.h"


char ssid[] = "Nokia 5"; // your network SSID (name)
char pass[] = "123456679"; // your network password
int keyIndex = 0;        // your network key Index number (needed only for WEP)

WiFiEspClient client;


unsigned long myChannelNumber_A = 963003;
const char * myWriteAPIKey_A = "T3U5VL0TBE9QCZRE";


unsigned long myChannelNumber_B = 964249 ;
const char * myWriteAPIKey_B = "K1EOTK98IDEB3ZIX";


#ifdef HAVE_HWSERIAL1
#include "SoftwareSerial.h"

SoftwareSerial Serial1(19, 18); // RX, TX
```

```
#define ESP_BAUDRATE 19200

#else

#define ESP_BAUDRATE 115200

#endif


// sensor ZMPT101B dihubungkan dengan pin A0

EnergyMonitor emon1;          // Create an instance


// Sensor ACS712_20A pada plta dihubungkan dengan pin A7
// Sensor ACS712_20A pada pltb dihubungkan dengan pin A8
// Sensor ACS712_20A pada plts dihubungkan dengan pin A5
// Sensor ACS712_20A pada aki dihubungkan dengan pin A6
// Sensor ACS712_20A pada keluaran ac dihubungkan dengan pin A9


ACS712 currentSensorplta(ACS712_20A, A7);
ACS712 currentSensorpltb(ACS712_20A, A6);
ACS712 currentSensorplts(ACS712_20A, A9);
ACS712 currentSensorac(ACS712_20A, A5);


//sensor pembagi tegangan pada PLTA
int analogInputplta = A3;

float voutplta = 0.0;

float vinplta = 0.0;

float R1 = 6200.0; //
float R2 = 24000.0; //

int valueplta = 0;
```

```
//sensor pembagi tegangan pada PLTB
```

```
int analogInputpltb = A2;
```

```
float voutpltb = 0.0;
```

```
float vinpltb = 0.0;
```

```
float R3 = 36000.0; //
```

```
float R4 = 51000.0; //
```

```
int valuepltb = 0;
```

```
//sensor pembagi tegangan pada PLTS
```

```
int analogInputplts = A1;
```

```
float voutplts = 0.0;
```

```
float vinplts = 0.0;
```

```
float R5 = 6800.0; //
```

```
float R6 = 24000.0; //
```

```
int valueplts = 0;
```

```
//sensor pembagi tegangan pada aki
```

```
int analogInputaki = A4;
```

```
float voutaki = 0.0;
```

```
float vinaki = 0.0;
```

```
float R7 = 12000.0; //
```

```
float R8 = 36000.0; //
```

```
int valueaki = 0;
```

```
//sensor pembacaan intensitas cahaya
```

```
BH1750 lightMeter;
```

```

// sensor pembacaan debit air

volatile int flow_frequency; // menghitung pulsa

float l_hour; // hitung liter/jam

unsigned char flowsensor = 3; // inputan Sensor

unsigned long currentTime;

unsigned long cloopTime;

void flow () // fungsi interrupt
{
    flow_frequency++;
}

// sensor anemometer

# define windPin 2 //Menerima data data dari sensor

// definisi konstanta

const float pi = 3.14159265; // nilai pi

int period = 1000; // perhitungan periode (milisecond)

int radio = 90; // jarak antara pusat windmill ke outer cup (mm)

int jml_celah = 18; // jumlah celah sensor

// Definisi variabel

unsigned int Sample = 0; // nilai sampel

unsigned int counter = 0; // B/W counter dari sensor

unsigned int RPM = 0; // Revolutions per minute

float speedwind = 0; // kecepatan angin (m/s)

void setup()
{
    Serial.begin(9600);

```

```
setEspBaudRate(ESP_BAUDRATE);

delay (100);

// calibrate() metode kalibrasi zero point pada sensor

// Pastikan arus tidak ada yang mengalir

//Serial.println("Mengkalibrasi....Pastikan tidak ada arus yang mengalir");

//delay(100);

emon1.voltage(A0, 600, 1.7); // Voltage: input pin, calibration, phase_shift


currentSensorplta.calibrate();

currentSensorpltb.calibrate();

currentSensorplts.calibrate();

currentSensorac.calibrate();

//Serial.println("Selesai!");


pinMode(analogInputplta, INPUT);

pinMode(analogInputpltb, INPUT);

pinMode(analogInputplts, INPUT);

pinMode(analogInputaki, INPUT);


Wire.begin();


lightMeter.begin();


pinMode(flowsensor, INPUT);

digitalWrite(flowsensor, HIGH); // Optional Internal Pull-Up

Serial.begin(9600);

attachInterrupt(0, flow, RISING); // Setup Interrupt
```

```
sei(); // Enable interrupts

currentTime = millis();

cloopTime = currentTime;


while (!Serial) {

    ; // wait for serial port to connect. Needed for Leonardo native USB port only
}


Serial.print("Searching for ESP8266...");

// initialize ESP module
WiFi.init(&Serial1);


// check for the presence of the shield
if (WiFi.status() == WL_NO_SHIELD) {

    Serial.println("WiFi shield not present");

    // don't continue

    while (true);

}

Serial.println("found it!");

ThingSpeak.begin(client); // Initialize ThingSpeak
}


void loop()

{

    // Connect or reconnect to WiFi

    if(WiFi.status() != WL_CONNECTED){
```

```

Serial.print("Attempting to connect to SSID: ");

Serial.println(ssid);

while(WiFi.status() != WL_CONNECTED){

    WiFi.begin(ssid, pass); // Connect to WPA/WPA2 network. Change this line if
using open or WEP network

    Serial.print(".");

    delay(3000);

}

Serial.println("\nConnected.");

}

emon1.calcVI(20,2000);    // Calculate all. No.of half wavelengths (crossings),
time-out

float U  = emon1.Vrms;      //extract Vrms into Variable

Serial.println(U);

delay(1000);

float Iplta = currentSensorplta.getCurrentDC();
float Ipltb = currentSensorpltb.getCurrentDC();
float Iplts = currentSensorplts.getCurrentDC();
float Iac = currentSensorac.getCurrentAC();

// Menghitung daya listrik yang digunakan

float Pplta = vinplta * Iplta;
float Ppltb = vinpltb*1.74 * Iplts*3;
float Pplts = vinplts * Iplts;

delay(1000);

```

```
// membaca nilai pada input analog PLTA
valueplta = analogRead(analogInputplta);
voutplta = (valueplta * 5.0) / 1024.0;
vinplta = voutplta / (R1/(R1+R2));
```

```
// membaca nilai pada input analog PLTB
valuepltb = analogRead(analogInputpltb);
voutpltb = (valuepltb * 5.0) / 1024.0;
vinpltb = voutpltb / (R3/(R3+R4));
```

```
// membaca nilai pada input analog PLTS
valueplts = analogRead(analogInputplts);
voutplts = (valueplts * 5.0) / 1024.0;
vinplts = voutplts / (R5/(R5+R6));
```

```
// membaca nilai pada input analog aki
valueaki = analogRead(analogInputaki);
voutaki = (valueaki * 5.0) / 1024.0;
vinaki = voutaki / (R7/(R7+R8));
```

```
//membaca nilai pada sensor BH1750
float lux = lightMeter.readLightLevel();
```

```
//membaca nilai pada sensor flowmeter
currentTime = millis();
```

```
// hitung dan print liter/jam setiap detik
```



```
if(currentTime >= (cloopTime + 1000))
{
    cloopTime = currentTime; // Updates cloopTime

    // frekuensi pulsa (Hz) = 7.5Q, Q adalah nilai aliran dalam L/min

    l_hour = (flow_frequency * 1 / 7.5); // (frekuensi pulsa x 60 min) / 7.5Q = flowrate
    dalam L/jam

    flow_frequency = 0; // Reset Counter

    Serial.print("Debit air: " );

    Serial.print(l_hour,3 ); // tampilkan liter/jam

    Serial.println(" Liter/menit");
}

Serial.print("INPUT V AC= ");
Serial.print(U,2);
Serial.println(" Volt");

Serial.print("INPUT V PLTA= ");
Serial.print(vinplta,2);
Serial.println(" Volt");

Serial.print("INPUT V PLTB= ");
Serial.print(vinpltb,2);
Serial.println(" Volt");

Serial.print("INPUT V PLTS= ");
Serial.print(vinplts,2);
Serial.println(" Volt");
```

```
Serial.print("INPUT V aki= ");
```

```
Serial.print(vinaki,2);
```

```
Serial.println(" Volt");
```

```
Serial.print("Arus Beban= ");
```

```
Serial.print(Iac,2);
```

```
Serial.println(" Ampere");
```

```
Serial.print("Arus PLTA= ");
```

```
Serial.print(Iplta,2);
```

```
Serial.println(" Ampere");
```

```
Serial.print("Arus PLTB= ");
```

```
Serial.print(Ipltb,2);
```

```
Serial.println(" Ampere");
```

```
Serial.print("Arus PLTS= ");
```

```
Serial.print(Iplts,2);
```

```
Serial.println(" Ampere");
```

```
Serial.print("Daya PLTA= ");
```

```
Serial.print(Pplta,2);
```

```
Serial.println(" Watt");
```

```
Serial.print("Daya PLTB= ");
```

```
Serial.print(Ppltb,2);

Serial.println(" Watt");


Serial.print("Daya PLTS= ");
Serial.print(Pplts,2);
Serial.println(" Watt");


Serial.print("Light: ");
Serial.print(lux);
Serial.println(" luxmeter");


//pembacaan sensor anemometer
int sensorValue = analogRead(2);

// print out nilai yang telah terbaca:
Serial.println(sensorValue);

Serial.print(Sample);

//Serial.print(": Mulai perhitungan...");

windvelocity();

//Serial.println(" Selesai.");

//Serial.print("Counter: ");

Serial.print(counter);

Serial.print("; RPM: ");

hitungRPM();

Serial.print(RPM);

Serial.print("; Kecepatan angin: ");

WindSpeed();
```

```
Serial.print(speedwind);

Serial.print(" [m/s]");

Serial.println();

delay(1000);


// set the fields with the values

ThingSpeak.setField(1, String(Pplta,2));
ThingSpeak.setField(2, String(Ppltb,2));
ThingSpeak.setField(3, String(Pplts,2));
ThingSpeak.setField(4, String(vinplts,2));
ThingSpeak.setField(5, String(Iplts,2));
ThingSpeak.setField(6, String(lux,2));
ThingSpeak.setField(7, String(U,2));
ThingSpeak.setField(8, String(Iac,2));


// write to the ThingSpeak channel

int x = ThingSpeak.writeFields(myChannelNumber_A, myWriteAPIKey_A);

if(x == 200){

    Serial.println("Channel update successful.");

}

else{

    Serial.println("Problem updating channel. HTTP error code " + String(x));

}

delay(6000);


ThingSpeak.setField(1, String(vinplta,2));
ThingSpeak.setField(2, String(Iplta,2));
```

```

ThingSpeak.setField(3, String(l_hour,2));

ThingSpeak.setField(4, String(vinpltb,2));

ThingSpeak.setField(5, String(Ipltb,2));

ThingSpeak.setField(6, String(speedwind,2));

ThingSpeak.setField(7, String(vinaki,2));


    int z = ThingSpeak.writeFields(myChannelNumber_B, myWriteAPIKey_B);
    if(z == 200){
        Serial.println("Channel update successful.");
    }
    else{
        Serial.println("Problem updating channel. HTTP error code " + String(z));
    }
    delay(6000);
}


// hitung kecepatan angin
void windvelocity()
{
    speedwind = 0;
    counter = 0;
    attachInterrupt(0, addcount, CHANGE);
    unsigned long millis();
    long startTime = millis();
    while(millis() < startTime + period) {}
    detachInterrupt(1);
}

```

```
void hitungRPM()
{
    RPM=((counter/jml_celah)*60)/(period/1000)*0.54; // Hitung revolutions per minute (RPM)
}

void WindSpeed()
{
    speedwind = (((2 * pi * radio * RPM)/60) / 1000)*2.438518; // Hitung kecepatan angin berdasarkan m/s
}

void addcount()
{
    counter++;
}

void setEspBaudRate(unsigned long baudrate){
    long rates[6] = {115200,74880,57600,38400,19200,9600};

    Serial.print("Setting ESP8266 baudrate to ");
    Serial.print(baudrate);
    Serial.println("...");

    for(int i = 0; i < 6; i++){
        Serial1.begin(rates[i]);
        delay(100);
        Serial1.print("AT+UART_DEF=");
        Serial1.print(baudrate);
        Serial1.print(",8,1,0,0\r\n");
    }
}
```

```
delay(100);
```

```
}
```

```
Serial1.begin(baudrate);
```

```
}
```

LAMPIRAN B
SCRIPT PERANGKAT KERAS SUB-SISTEM TAMBAHAN : ATS

```
#include "DS3231_Simple.h"

#include <Wire.h>

DS3231_Simple Clock;

void setup() {
    Serial.begin(9600);
    Clock.begin();
}

void loop() {
    DateTime waktu;
    waktu = Clock.read();
    if ((Clock.read() >= 18) || (Clock.read() < 20)) {    // kondisi pukul 18 - 6
        // digitalWrite(pinRelay, HIGH);                // relay HIGH, lampu nyala
        Serial.print("Lampu nyala");                    // #debug
    } else {
        //digitalWrite(pinRelay, LOW);                    // relay LOW, lampu mati
        Serial.print("Lampu mati");                      // #debug
    }

    Serial.print(waktu.Day);
    Serial.print("/");
```



```
Serial.print(waktu.Month);  
  
Serial.print("/");  
  
Serial.print(waktu.Year);  
  
Serial.print(" ");  
  
Serial.print(waktu.Hour);  
  
Serial.print(":");  
  
Serial.print(waktu.Minute);  
  
Serial.print(":");  
  
Serial.println(waktu.Second);  
  
  
delay(1000);
```

LAMPIRAN C

RINCIAN DATA PENGUJIAN

Tabel 6.1 Hasil Pembacaan Tegangan, Arus dan Daya Bangkit

Volume (liter)	Waktu (detik)	Tegangan (V)	Arus (A)	Daya(W)
1	3.76	5.46	0.05	0.273
2	7.57	6.24	0.16	0.9984
3	11.07	8.45	0.18	1.521
4	15.29	8.43	0.19	1.6017
5	18.43	8.78	0.28	2.4584
6	22.36	9.08	0.39	3.5412
7	25.88	9.1	0.51	4.641
8	29.92	9.82	0.62	6.0884
9	33.34	10.17	0.61	6.2037
10	37.12	10.09	0.75	7.5675

Tabel 6.2 Hasil Pembacaan Volume terhadap Tegangan

Volume(liter)	Tegangan(V)
1	5.46
2	6.24
3	8.45
4	8.43
5	8.78
6	9.08
7	9.1
8	9.82
9	10.17
10	10.09

Tabel 6.3 Hasil Pembacaan Volume terhadap Arus

Volume (liter)	Arus (A)
1	0.05
2	0.16
3	0.18
4	0.19
5	0.28
6	0.39
7	0.51
8	0.62
9	0.61
10	0.75

Tabel 6.4 Hasil Pembacaan Volume terhadap Waktu

Volume (liter)	Waktu (detik)
1	3.76
2	7.57
3	11.07
4	15.29
5	18.43
6	22.36
7	25.88
8	29.92
9	33.34
10	37.12

Tabel 6.5 Hasil Pembacaan Volume dan Waktu terhadap Debit

Volume (liter)	Waktu (menit)	Debit (L/menit)
1	0.0627	15.95745
2	0.1262	15.85205
3	0.1845	16.26016
4	0.2548	15.69653
5	0.3072	16.27781
6	0.3727	16.10018
7	0.4313	16.22875
8	0.4987	16.04278
9	0.5557	16.19676
10	0.6187	16.16379

Tabel 6.6 Hasil Pembacaan Volume terhadap Daya

Volume (liter)	Daya (W)
1	0.273
2	0.9984
3	1.521
4	1.6017
5	2.4584
6	3.5412
7	4.641
8	6.0884
9	6.2037
10	7.5675